

# The analog data assimilation: method, applications and implementation

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# Before starting

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## Who am I:

Brest, France

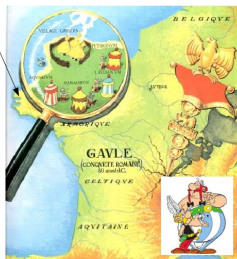
Main oceanographic  
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My engineering  
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IMT Atlantique  
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- ▶ Master in applied mathematics
- ▶ PhD in spatial oceanography (IFREMER, France)
- ▶ Postdoc in atmospheric sciences (Univ. Corrientes, Argentina)
- ▶ Postdoc and Associate Professor (IMT-Atlantique, France)

# General Concept

## Classic

## Data

## Assimilation

$$\frac{dx_1}{dt} = \sigma(x_2 - x_1)$$

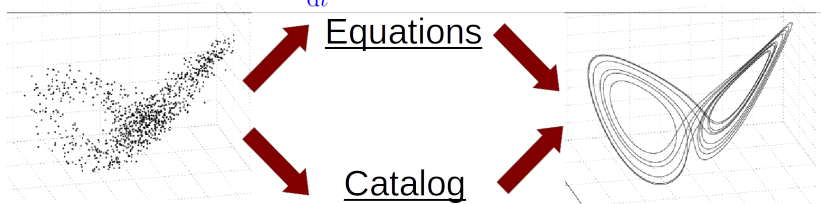
→ model-driven

$$\frac{dx_2}{dt} = x_1(\rho - x_3) - x_2$$

→ model integration needed

→ high computational cost

$$\frac{dx_3}{dt} = x_1x_2 - \beta x_3$$



## Analog

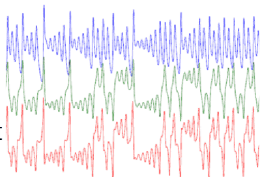
## Data

## Assimilation

→ data-driven

→ statistical emulator

→ low computational cost



# Outline

## Analog forecasting

- General formulation
- Different implementations

## Analog data assimilation

- Comparison with model-driven approach
- General implementation

## Experimental settings

- Classic VS analog data assimilation
- Analog data assimilation for model evidence
- Global VS local analog strategies

## Applications

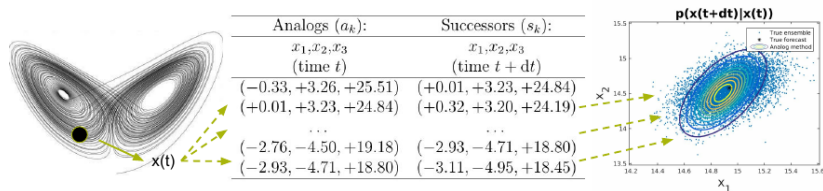
- Using satellite data
- Using numerical simulations

## Conclusions and perspectives

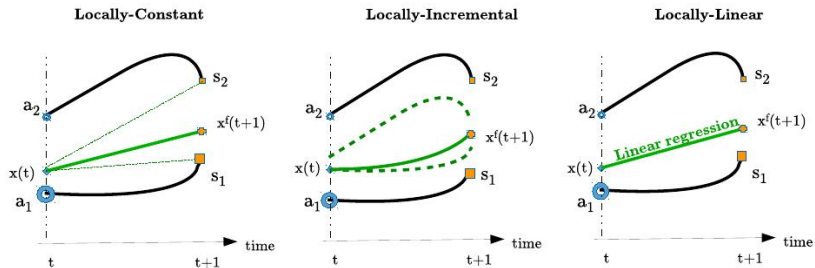
- Conclusions
- Perspectives
- AnDA references

# Analog forecasting (general formulation)

- ▶ State of the art:
  - ▶ introduced by [Lorenz, 1969]
  - ▶ destroyed by [Van Den Dool, 1994]
  - ▶ revival (large datasets + machine learning) by [Zhao and Giannakis, 2016]
- ▶ Analog forecasting:
  - ▶ use historical datasets (observations, simulations)
  - ▶ use the k-nearest neighbors
  - ▶ emulate the dynamical model

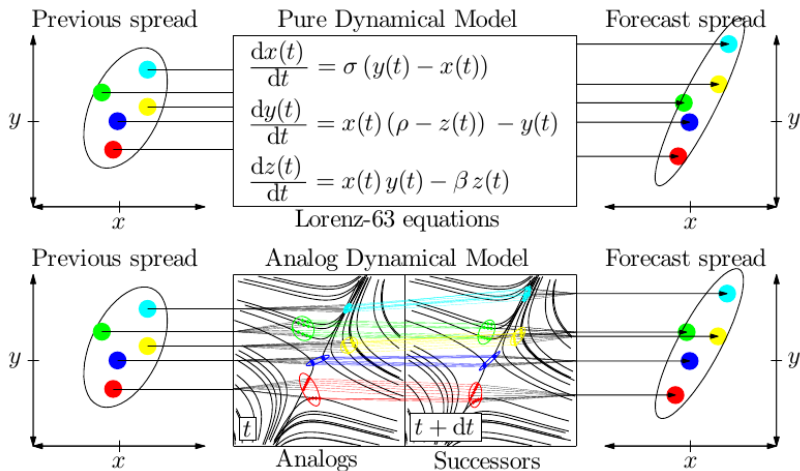


# Analog forecasting (different implementations)



- ▶ Weighted mean of the successors (locally constant):  
$$x^f(t+1) = \sum_{k=1}^K \omega_k [x(t)] s_k [x(t)]$$
- ▶ Weighted mean of the increments (locally incremental):  
$$x^f(t+1) = x(t) + \sum_{k=1}^K \omega_k [x(t)] (s_k [x(t)] - a_k [x(t)])$$
- ▶ Regression between analogs and successors (locally linear):  
$$x^f(t+1) = \beta_0 [x(t)] + \beta_1 [x(t)] x(t)$$

# Analog data assimilation (model-driven VS data-driven)



⇒ Share the same sequential framework (Kalman/particle filter)

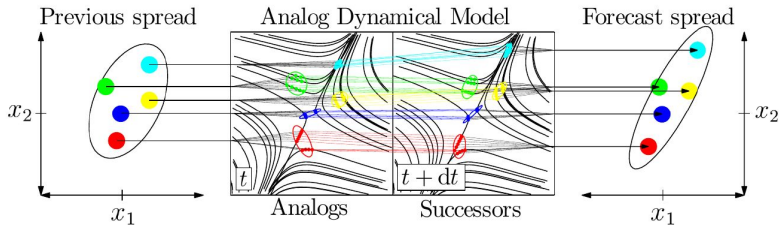
# Analog data assimilation (general implementation)

Nonlinear state-space model (analog forecasting operator  $\mathcal{A}$ ):

$$\mathbf{x}(t) = \mathcal{A}(\mathbf{x}(t - dt), \boldsymbol{\eta}(t)) \quad (1)$$

$$\mathbf{y}(t) = \mathbf{H}\mathbf{x}(t) + \boldsymbol{\epsilon}(t) \quad (2)$$

Sequential implementation:



## Step 0:

- start from last analysis step (time  $t$ )
- $N$  members with same weights (EnKF)
- $N$  particles with different weights (PF)

## Step 1:

- find  $K$  nearest analogs ( $\mathbf{a}_1, \dots, \mathbf{a}_K$ )
- compute their weights ( $w_1, \dots, w_K$ )
- use appropriate distance/kernel

## Step 2:

- combine the  $K$  successors ( $\mathbf{s}_1, \dots, \mathbf{s}_K$ ) using ( $w_1, \dots, w_K$ )
- different analog forecasting strategies (constant, incremental, linear)

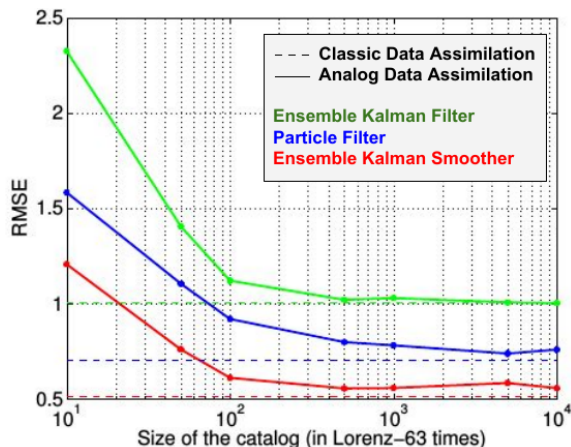
## Step 3:

- different sampling schemes (Gaussian, multinomial)
- compare forecasts to noisy observations
- recombine  $N$  members (EnKF) or particles (PF)

$t \leftarrow t+1$



# Experimental settings (model-driven VS data-driven)



- ▶ simulated data (Lorenz-63)
- ▶ 1 obs. variable ( $x_1$  with  $R=2$ )
- ▶ partial obs. (8 time steps)

Figure 1: Effect of filtering method and catalog size on state reconstruction

⇒ Equivalence for large enough catalog size

## Experimental settings (model evidence)

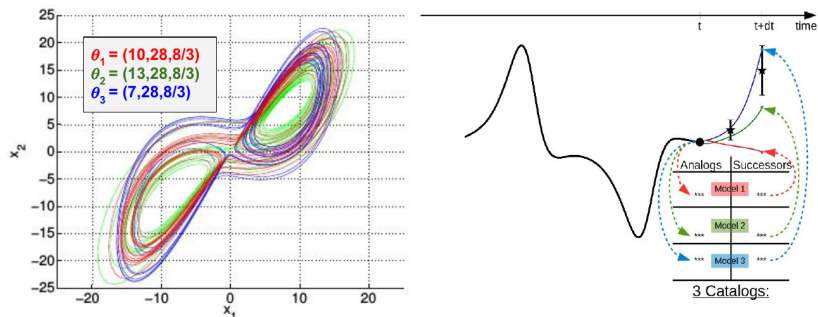
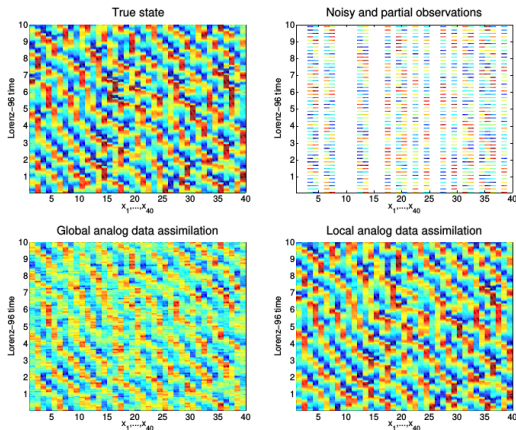


Figure 2: Scheme of the Analog Data Assimilation with various catalogs

- ▶ same previous experiment
- ▶ 3 catalogs with different parameters ( $\theta_1$ ,  $\theta_2$ ,  $\theta_3$ )
- ▶ obs. generated with  $\theta_1$

⇒ Able to retrieve the good parameterization:  
 $\theta_1$  (61%),  $\theta_2$  (27%),  $\theta_3$  (12%)

# Experimental settings (global VS local analogs)



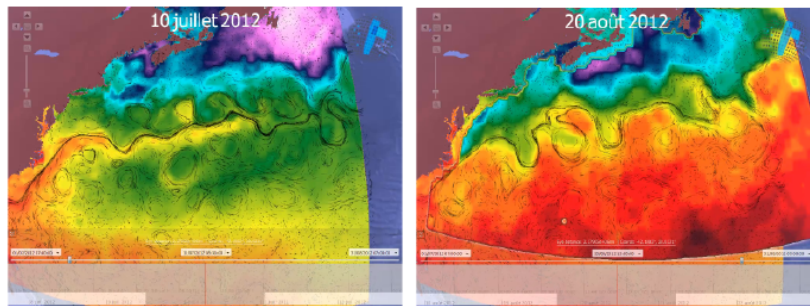
- ▶ simulated data (Lorenz-96)
- ▶ 20 obs. variables (noise  $R=2$ )
- ▶ partial obs. (4 time steps)

Figure 3: Effect of local and global analogs on state reconstruction

⇒ Local analog strategy outperforms the global one

## Applications (use of satellite historical datasets)

- ▶ Daily and mesoscale datasets
- ▶ Synergy between satellite sources
- ▶ Large number of already seen situations (e.g., eddy motion)



**Figure 4:** Surface observations of temperature (left, 40 years) or salinity (right, 10 years) with oceanic currents (both, 25 years). Full animation: <https://www.youtube.com/watch?v=Wn5grSFPQFA>.

# Applications (results exploiting satellite historical datasets)

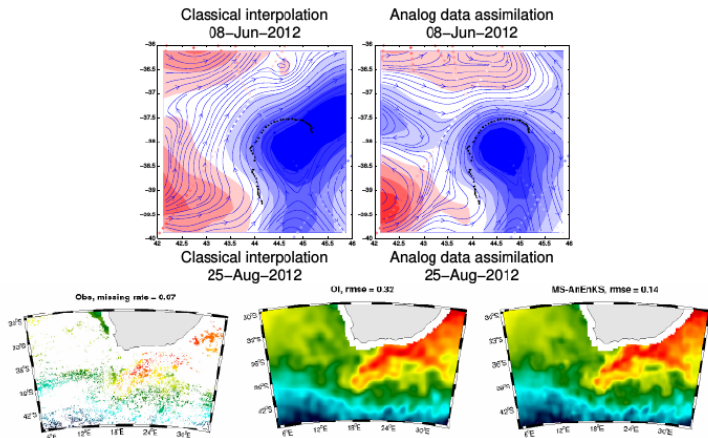


Figure 5: Comparison between classic interpolation and interpolation based on analogs for ocean currents (top) and temperatures (bottom).

⇒ Analog-based interpolations learn adaptively: advection, diffusion and spatial correlation lengths.

# Applications (use of ensemble simulations)

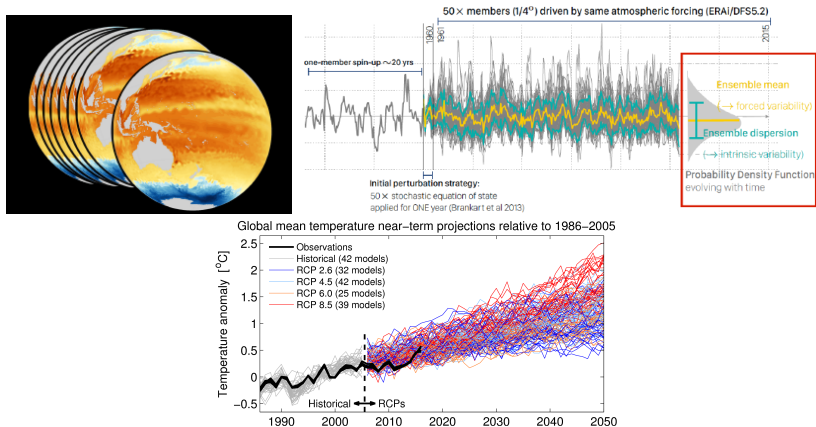


Figure 6: Examples of ensemble simulations in oceanography (OCCIPUT dataset, top) and in climate (CMIP dataset, bottom).

⇒ 2 ongoing projects in oceanography (comparison with classic data assimilation) and meteorology/climate (model evidence)

# Conclusions

- ▶ Data-driven assimilation  
(exploit historical datasets: observations, simulations)
- ▶ Various implementations  
(global/local analogs, AnEnKF/AnPF/AnEnKS)
- ▶ Easy, fast and flexible, especially for local/partial analysis  
(compared to model-driven data assimilation)
- ▶ Python library on GitHub  
(<https://github.com/ptandeo/AnDA>)

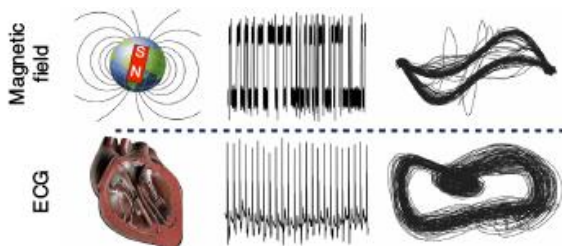
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**ptandeo** Update README.md    Latest commit 698d9e6 Dec 23, 2017

<a href="#">.ipynb_checkpoints</a>	AnDA_V1	a year ago
<a href="#">AnDA_codes</a>	AnDA_V1	a year ago
<a href="#">README.md</a>	Update README.md	2 months ago
<a href="#">test_AnDA.ipynb</a>	AnDA_V1	a year ago

# Perspectives



- ▶ Methodology:
  - ▶ transform raw data into attractor (see [Brunton et al., 2017])
  - ▶ automatic distance learning
  - ▶ other possible forecast operators (e.g., neural nets)
- ▶ Applications:
  - ▶ complex dynamical systems  
(ecology, meteorology/climate, medicine, etc...)
  - ▶ no available models and lot of data
- ▶ Collaborations are welcome!



# AnDA References

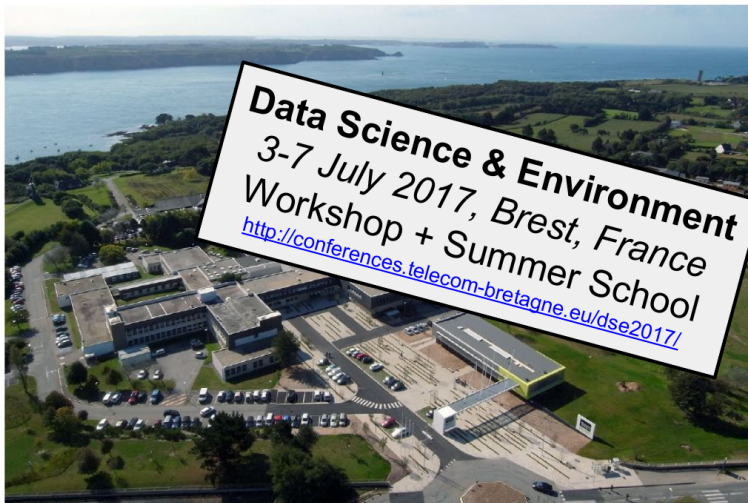
## Methodological publications:

- ▶ Lguensat et al. 2017, **The Analog Data Assimilation**, *Monthly Weather Review*
- ▶ Tandeo et al. 2015, **Combining Analog Method and Ensemble Data Assimilation: Application to the Lorenz-63 Chaotic System**, *Machine Learning and Data Mining Approaches to Climate Science (Springer)*
- ▶ Tandeo et al. 2014, **The Analog Ensemble Kalman Filter and Smoother**, "Climate Informatics" workshop, Boulder (CO)

## Application publications:

- ▶ Fablet et al. 2017, **Data-driven Methods for Spatio-Temporal Interpolation of Sea Surface Temperature Images**, *IEEE Transactions on Computational Imaging*
- ▶ Tandeo et al. 2015, **The Analog Data Assimilation: Application to 20 Years of Altimetric Data**, "Climate Informatics" workshop, Boulder (CO)

# IMT-Atlantique: Birthplace of AnDA







**Data Science & Environment**  
**3-7 July 2017, Brest, France**  
**Workshop + Summer School**  
<http://conferences.telecom-bretagne.eu/dse2017/>

**Thank you for your attention!**  
**Any questions?**

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## Cited references

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