

Estimation of key parameters in cloud microphysics using ensemble Kalman filter

Kenta Sueki

RIKEN Center for Computational Science

Computational Climate Science Research Team

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Introduction

Toward the improvement of weather prediction

- ✓ **Better model** ←
- ✓ Better observation
- ✓ Better data assimilation method

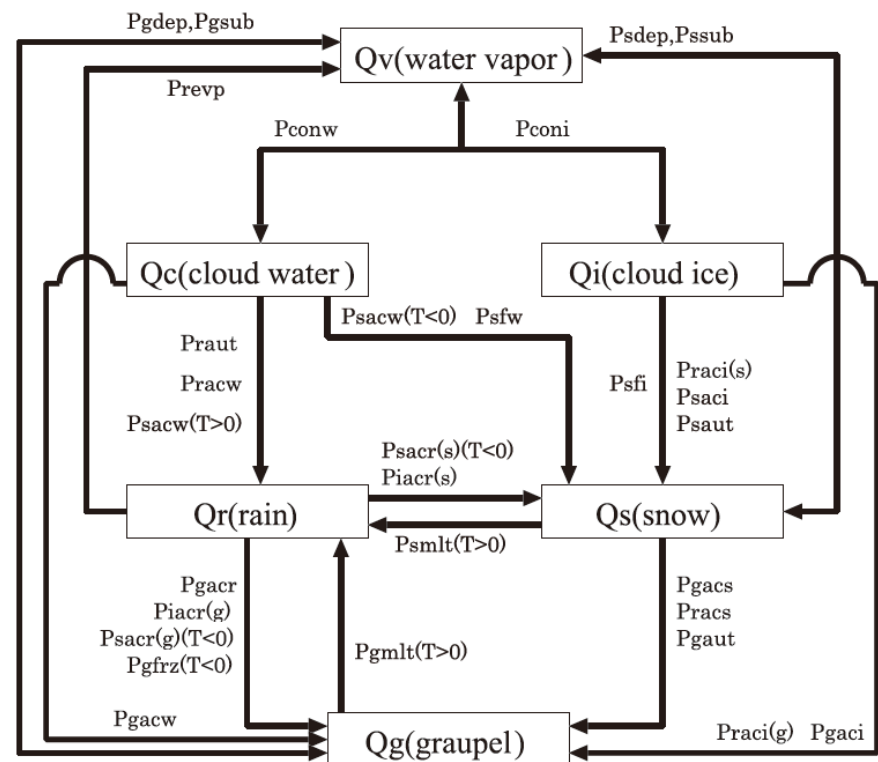
Using data science



Introduction

More specifically...

- Components of atmospheric model
 - Dynamical core, cloud microphysics, turbulence, radiation, ...
- In the precipitation forecast, performance of **cloud microphysics scheme** is particularly important
- Simple bulk microphysics schemes are widely used
 - Many **"tunable" parameters**
 - ✓ Terminal velocity,
 - ✓ Auto-conversion rate,
 - ✓ Collection efficiency, ...



Tomita (2008), JMSJ, Fig. 1

Introduction

“Optimal” parameter values depend on the situation

- Space and time scales to be simulated
 - Short-term weather forecast ↔ Long-term climate prediction
- Metrics of interest
 - Rainfall amount, radiation budget, ...

We focus on **short-term heavy rainfall prediction**

- Need good representation of lifecycle and organization of deep convective clouds

Introduction

But how?

—Parameter estimation using ensemble Kalman filter (EnKF)

- **Tong and Xue (2008), MWR**

- ✓ **Target:** Size distribution of hail, etc
- ✓ **Observation:** Radar reflectivity calculated from cloud simulation with known parameter values

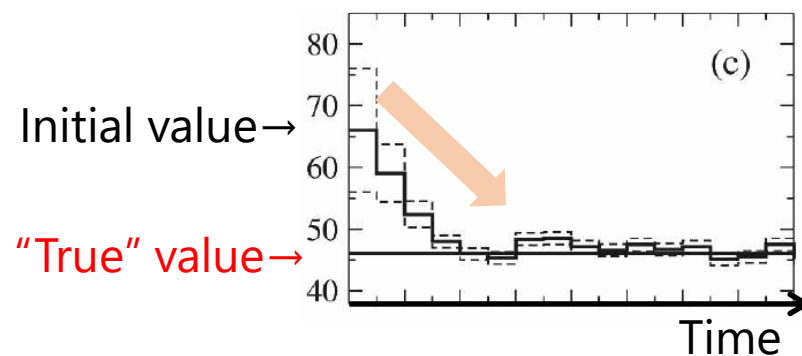


Fig. 1c

- **Kotsuki et al. (2018), JGR**

- **Target:** Conversion rate of cloud water to rain
- **Observation:** Global precipitation distribution

Original value

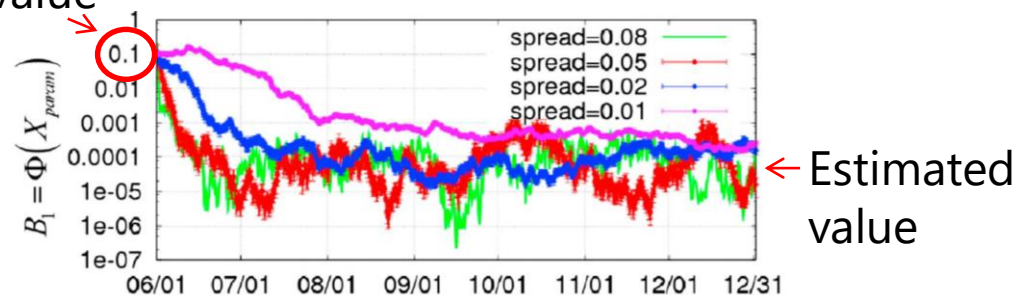


Fig. 4b

Introduction

- **Final goal:**

Find optimal parameters of cloud microphysics scheme focusing on short-term heavy rainfall prediction

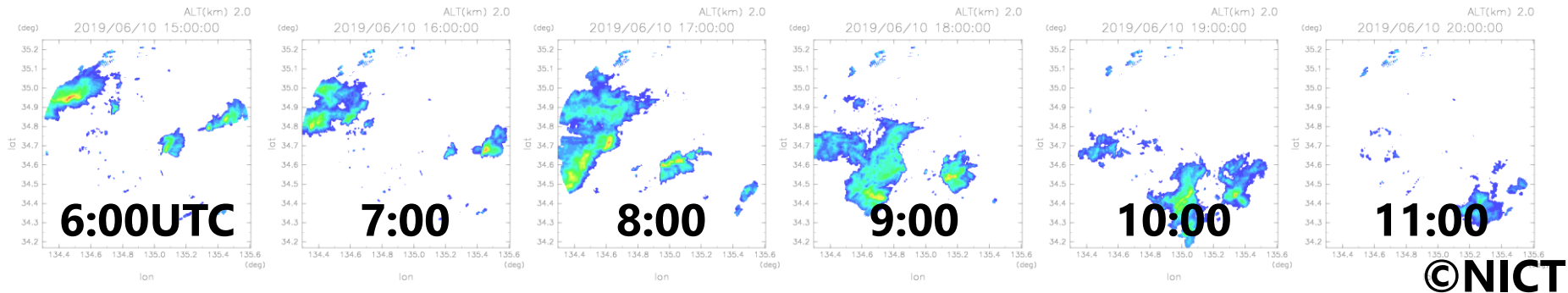
- **Present study:**

Test parameter estimation using the EnKF based method with radar reflectivity data

Today, I introduce our recent efforts to estimate optimal parameters of cloud microphysics scheme

Real data experiments

Case study: Thunderstorm on 10 July 2019



- Well captured by phased array weather radar (PAWR) in Kobe city
 - 3D reflectivity and doppler velocity, **every 30 second**

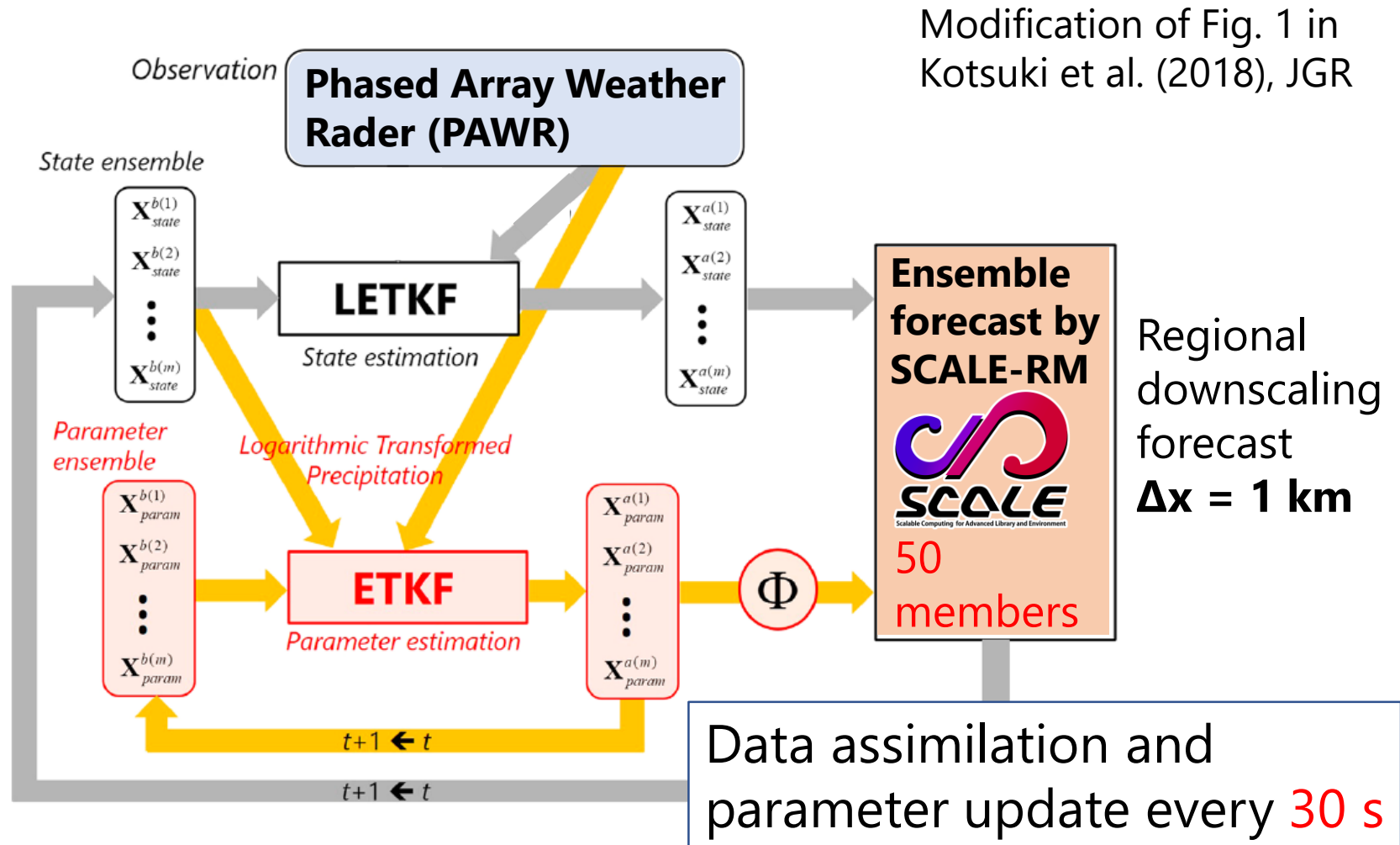
Components of state and parameter estimations

- **Forecast model:** **SCALE-RM** (Nishizawa et al. 2015; Sato et al. 2015)
- **Observation:** PAWR
- **State estimation:** Local ensemble transform Kalman filter (**LETKF**; Hunt et al. 2007) (**SCALE-LETKF system**; Lien et al., 2017)
- **Parameter estimation:** No-localized ETKF

Real data experiments

Schematics

- The figure from Kotsuki et al. (2018)



Real data experiments

Target parameter

- **Scheme:** One-moment bulk microphysics (Tomita 2008)
 - Choose **coefficient of terminal velocity of rain (Cr)** as the first test case

$$V_R = \text{Cr} \left(D_R \frac{\rho_0}{\rho} \right)^{1/2} \quad V_R \propto \text{Cr}$$

(Default value: **Cr = 130**)

- Why "Cr"?
 - ✓ Directly changes the radar reflectivity distribution
 - ✓ Greatly impacts the rainfall amount

Real data experiments

Results

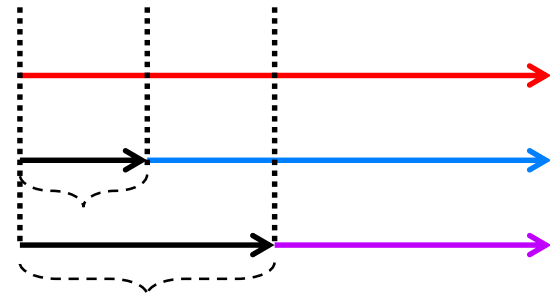
- Different initial time

PE from 06:00UTC

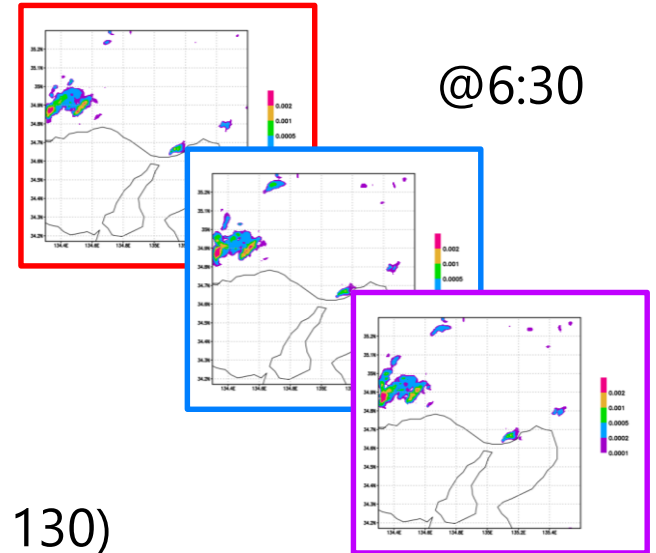
PE from 06:10UTC

PE from 06:20UTC

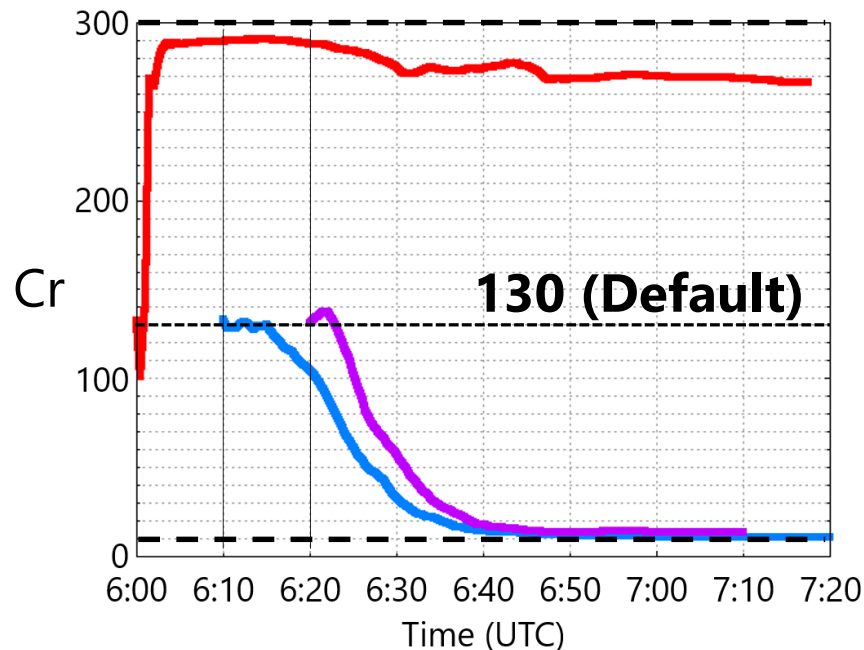
6:00 6:10 6:20



DA w/o PE (constant $Cr = 130$)



@6:30



- Converged value depends on the initial time
- The value approaches to the preset maximum or minimum

*Hmm...
It's difficult*

Real data experiments

Many challenges in achieving parameter estimation using radar observation of real clouds

- Large time fluctuation,
- Inconsistency between “nature” and model resolution,
- In addition, the experiments are computationally costly, ...

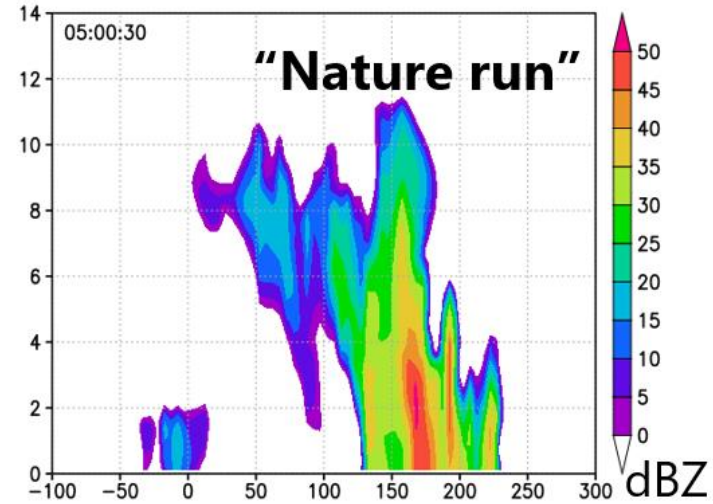
➤ Back to simpler “idealized” experiments

Idealized experiments

Idealized 2D (x-z) squall line simulation

- $\Delta x = 5 \text{ km}$, $\Delta z = 250 \text{ m}$
- Tomita (2008) microphysics ($Cr = 130$)
- Horizontally homogeneous initial condition (Same as Weisman and Klemp 1982)

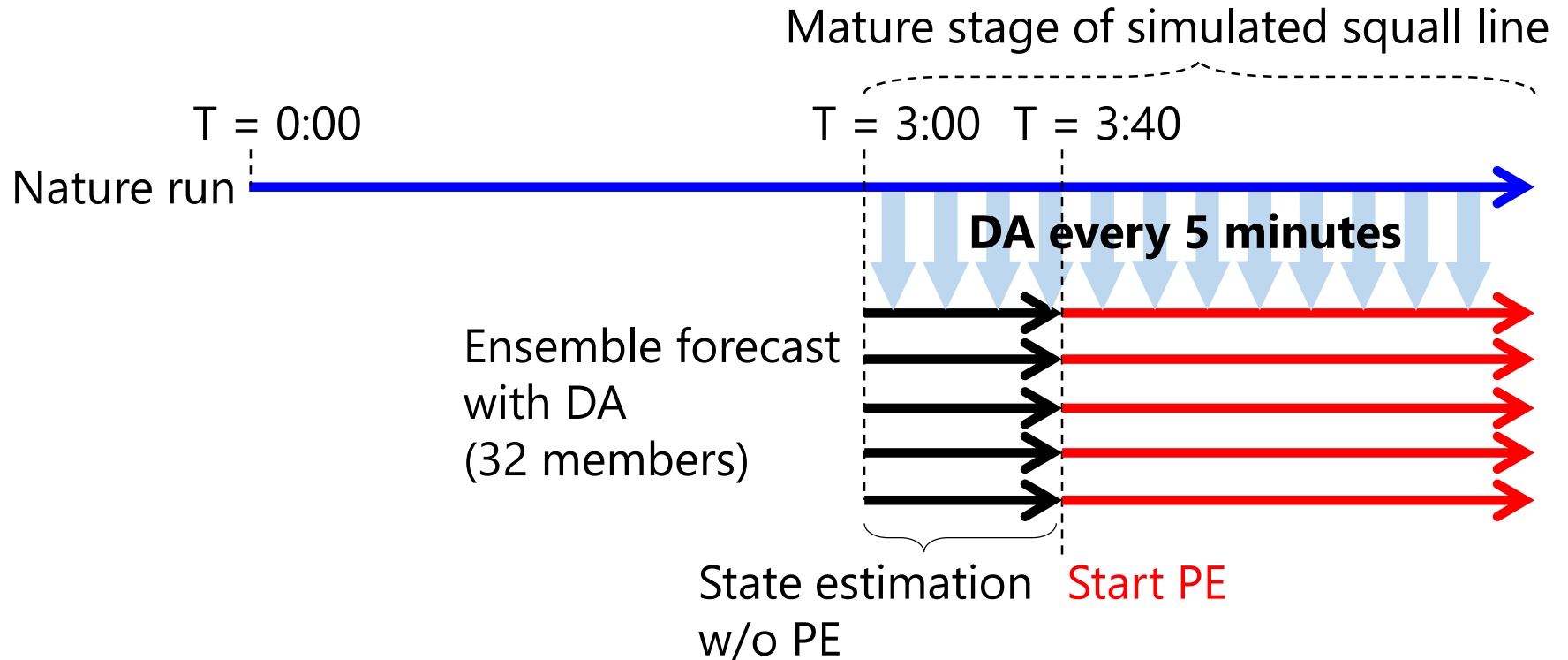
- State estimation by LETKF
- Parameter (Cr) estimation by ETKF
 - ✓ Same model setup as nature run except the parameter to be estimated
 - ✓ 32 ensemble members
 - ✓ 5 minutes DA cycle
 - ✓ Observation error assumption: 1 dBZ



Observation

Idealized experiments

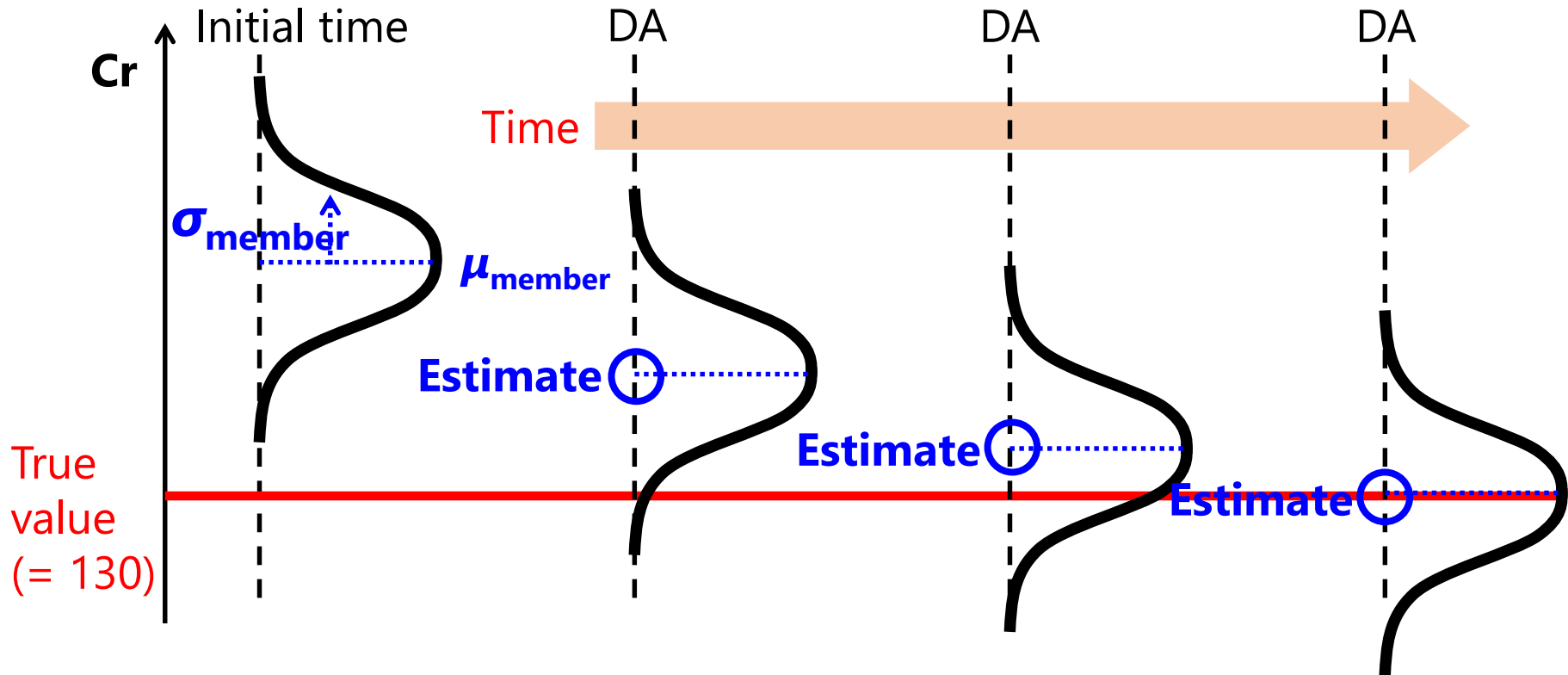
Timeseries



Idealized experiments

Concept

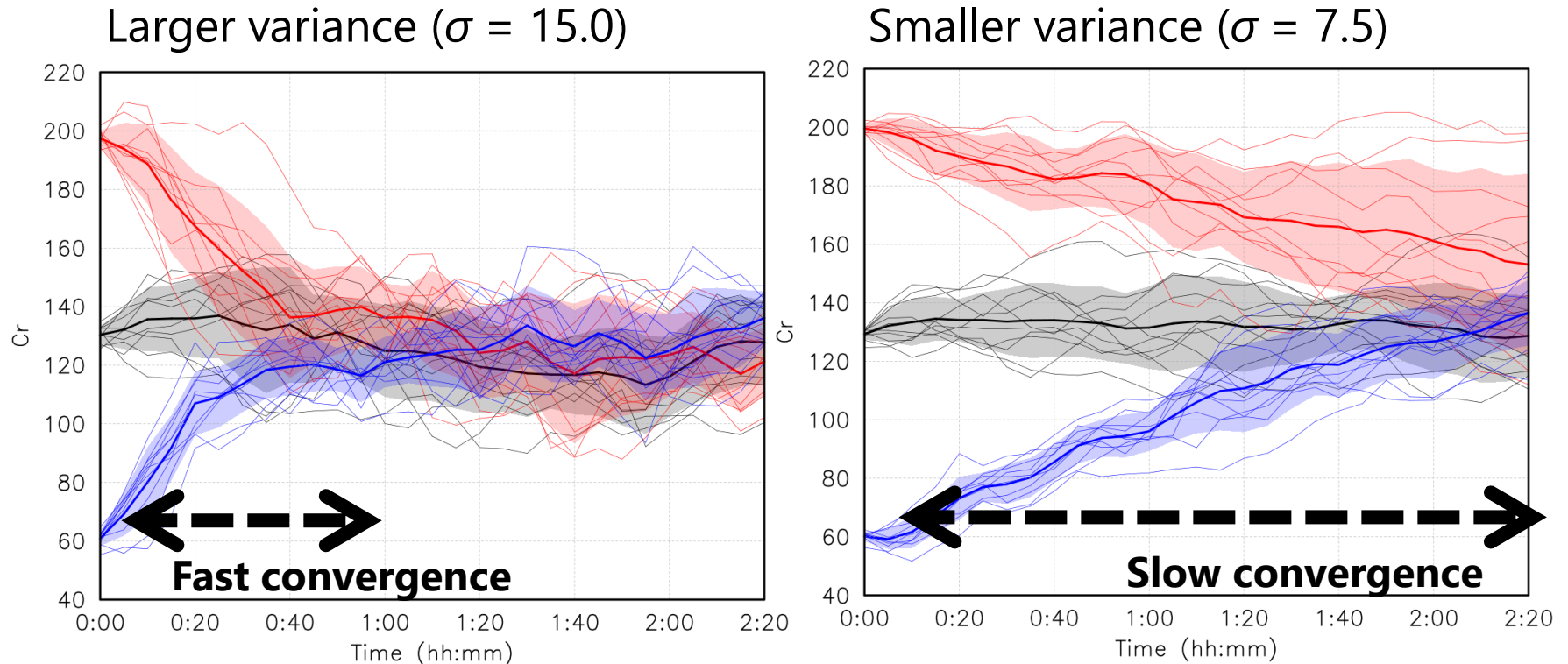
- Test the **feasibility** of parameter estimation for cloud microphysics



- Initial Cr distribution for 32 ensemble members (**Gaussian**)
 - ✓ Mean (μ_{member}): **200** ($= \text{true} + 70$), **60** ($= \text{true} - 70$), and **130** ($= \text{true}$)
 - ✓ Standard deviation (σ_{member}): **7.5**, **15**

Idealized experiments

Results 1: Convergence speed to true value

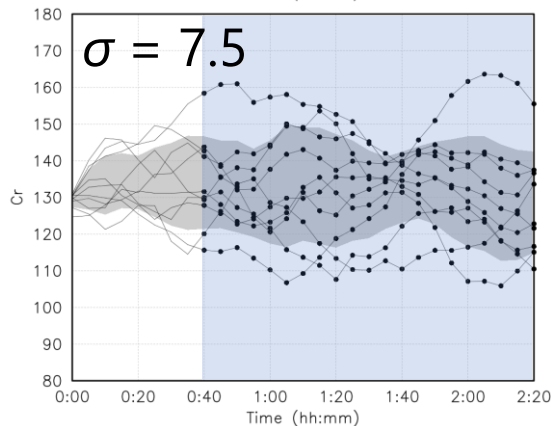
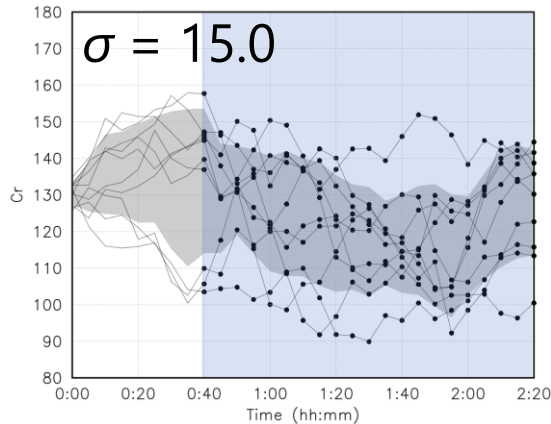


*10 trials with slightly different initial Cr values for each experiment

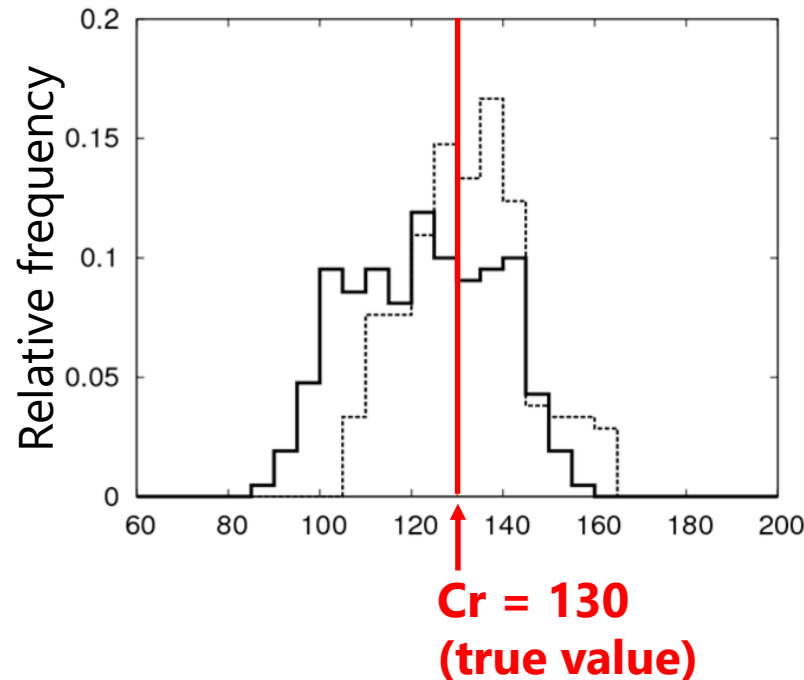
- Estimations start from $\mu_{\text{member}} = 200$ and 60 approach the true value
 - If the model is perfect, **estimation of Cr from radar data is possible!**
- Ensembles having **larger variance converge quickly**

Idealized experiments

Results 2: Estimation accuracy



Distribution of estimated Cr values after 40 minutes



Solid line:

$\sigma_{\text{member}} = 15.0$

➤ Mean = 122.6

➤ Standard deviation = 15.6

Broken line:

$\sigma_{\text{member}} = 7.5$

➤ Mean = 131.9

➤ Standard deviation = 13.0

- Comparison of the uncertainty: $15.6 > 13.0$ by the F test
 - Ensembles having **smaller variance provide smaller uncertainty** of the estimation

Summary

- We have started the efforts to estimate **the optimal parameters for cloud microphysics scheme** by using the EnKF based method
- Parameter estimation based on real radar observation is challenging at present
- Idealized experiments show the feasibility of parameter estimation for cloud microphysics
- We found that **estimation speed and accuracy are trade-off**

On going research

- Clarify the **optimal ensemble variance** for estimating the true value with the highest accuracy
- Discuss relationships between the accuracy of parameter estimation and deep convection dynamics
- Test **other key parameters** such as terminal velocity of snow, graupel, and evaporation rate of rain