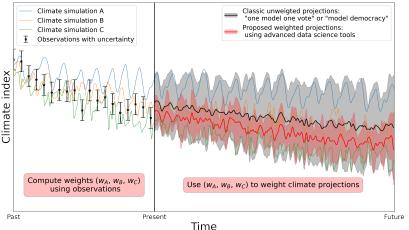
Narrowing uncertainties in climate projections using data science tools

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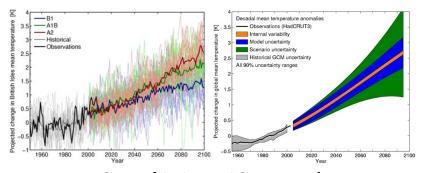
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IMT-Atlantique & RIKEN Online Joint Seminar Series

Context and main goal



- ▶ In the IPCC \rightarrow ensemble of **unweighted projections** ("one model one vote" or "model democracy", [Knutti, 2010])
- Idea → learn weights from historical observations and simulations, then propagate weights to climate projections

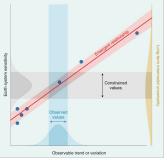
Climate uncertainties revealed by CMIP



Source: [Hawkins and Sutton, 2011]

- Climate projections are sensitive to internal, <u>model</u> and scenario uncertainties
- Potential to narrow uncertainties, especially in regional climate predictions [Hawkins and Sutton, 2009]

New at IPCC: emergent constraints



Source: [Eyring et al., 2019]

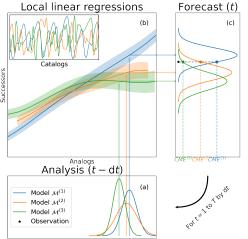
Pros:

- ► Easy to implement (projection using linear regression)
- Easy to understand (synthetic graphical representation)
- ▶ Do not weight climate simulations (not directly)

Cons:

- Causality not obvious (especially for large horizons)
- Low number of samples to fit the regression
- Questionable linear relationship and homoscedasticity

Proposed approach: use advanced data science methods



Three main steps:

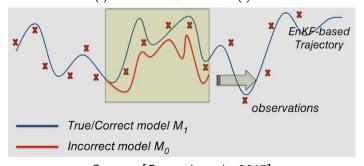
- ▶ (a) Data assimilation (ensemble Kalman filter)
- ▶ (b) Data-driven forecasting (local linear regression)
- (c) Distance obs-forecasts (contextual model evidence)

Ingredient 1: (a) EnKF + (c) contextual model evidence

Contextual model evidence in data assimilation (CME):

$$\mathcal{L}\left(\mathbf{y}(t)|\mathcal{M}_{(i)}\right) \propto \exp\left(-\mathsf{d}_{(i)}(t)^{\top}\boldsymbol{\Sigma}_{(i)}(t)^{-1}\mathsf{d}(t)\right) \tag{1}$$

with the **innovation** defined by its mean and covariance: $d_{(i)}(t) = y(t) - Hx_{(i)}^f(t)$ and $\Sigma_{(i)}(t) = HP_{(i)}^f(t)H^\top + R$.



Source: [Carrassi et al., 2017]

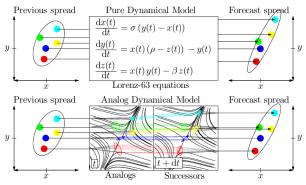
Ingredient 2: (a) EnKF + (b) analog forecasting

Analog forecasting within data assimilation (AnDA):

$$x(t) = A(x(t - dt), \eta(t))$$
 (2)

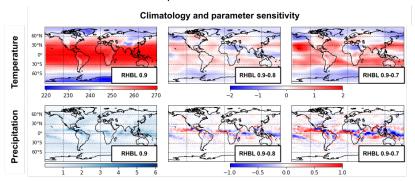
$$y(t) = \mathcal{H}(x(t)) + \epsilon(t)$$
(3)

with A the **analog forecasting** operator [Lguensat et al., 2017].



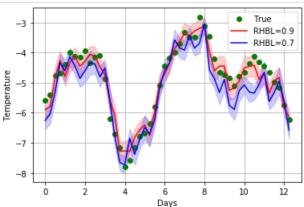
Source: [Tandeo et al., 2015]

- ► Tested on a **simplified GCM** (SPEEDY, [Molteni, 2003]):
 - ▶ 7 vertical levels, 96 × 48 horizontal grid
 - ▶ simple physics (<u>convection</u>, clouds, radiation, boundary layer)
- ▶ Relative Humidity threshold in the Boundary Layer:
 - ightharpoonup RHBL = 0.9 ightharpoonup the "true" model
 - ▶ RHBL = $0.8 \rightarrow \text{slightly imperfect model}$
 - ightharpoonup RHBL = 0.7 ightharpoonup imperfect model

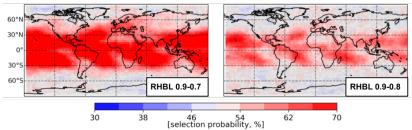


- Analog data assimilation details:
 - ▶ EnKF with 40 members with adaptive inflation [Miyoshi, 2011]
 - ▶ 30-years catalogs for 3 parameterizations (RHBL 0.9, 0.8, 0.7)
 - ▶ 3D local domains (3 vertical levels, 3 × 3 horizontal grid)
 - ▶ 3 years of noisy observations from RHBL 0.9 (std = 0.7K)

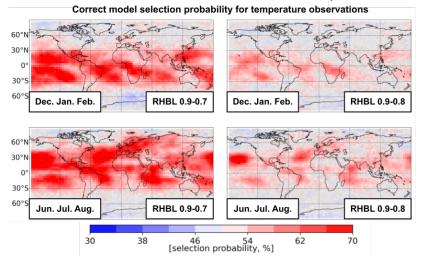
Filtering results using AnDA with 2 catalogs (RHBL=0.9 & RHBL=0.7)



Correct model selection probability for temperature observations



- ▶ Results about model identification (in space):
 - tropical-subtropical regions affected by model imperfections
 - ▶ degree of imperfection is captured (RHBL 0.7 < 0.8)



- Results about model identification (in space and time):
 - sensibility to the RHBL parameter is evolving in time
 - detection of model imperfection more important in summers (i.e., when there is more convection observed)

Conclusions:

- Combination of advanced data-science methods
- Able to compare short-term model dynamics
- Ruiz et al., will be submitted soon to the Journal of Climate

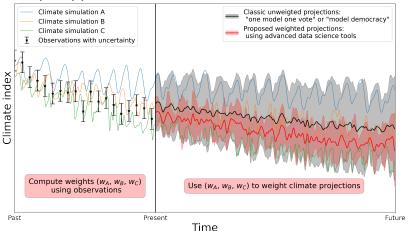
Pros:

- Local approach (sub-domain, given period, partial variables)
- Low-cost procedure (no need to run climate models)
- Capture spatiotemporal differences in model identifications

Cons:

- Need historical numerical simulations
- ▶ Need tuning (analogs, inflation, domain, observations)
- May seem complicated (but not so much!)

Next step: application to climate simulations

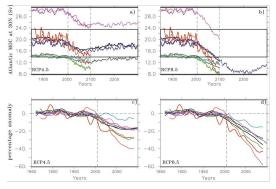


- Data → compare current observations to CMIP simulations
- Method → combine data-science methods (DA, AF, CME)
- lacktriangle Goal 1 o create weighted projections of climate metrics
- ▶ Goal $2 \rightarrow$ reduce the uncertainty of climate projections

Next step: application to climate simulations

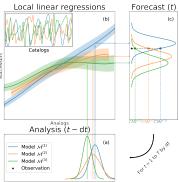
Specificity of climate simulations [Knutti et al., 2019]:

- Interdependence → many CMIP models share ideas, parts of code, or whole components (e.g., the sea ice model)
- Performance → some CMIP models are "good" at representing a specific climate index, other models are not
- Simulations are sometimes **biased** and need **standardization**AMOC variations in CMIP5 for 2 RCP scenarios



Source: [Cheng et al., 2013]

Next step: application to climate simulations



Caveats and improvement of the methodology:

- (a) → deal with model interdependence (e.g., work with clusters of models), deal with non-parametric distributions
- (b) → find differences in the short-term dynamics of climate metrics (especially in the extremes), find relevant dt
- (c) → define more flexible metrics (e.g., optimal transport), find relevant observations (long time series, knowing noise)

Thank you for your attention! Any questions?

MAFALDA:

Multi-climate-model Analog Forecasting for Attributing Likelihoods using Data Assimilation



French ANR program
JCJC "young researcher"
Under evaluation (2nd round)



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